

0.1 stepped pressure equilibrium code : readme

1. The stepped pressure equilibrium code.
2. The stepped pressure equilibrium code [1] seeks numerical solutions to macroscopic force balance between the pressure gradient and the Lorentz force in arbitrary, non-axisymmetric toroidal configurations, with fields of arbitrary topology. Generally, non-axisymmetric toroidal magnetic fields are non-integrable, so the magnetic field is not guaranteed to be tangential to a set of continually nested magnetic surfaces.
3. Equilibrium solutions are cast as extrema of a constrained energy functional.
4. Consider a plasma region comprised of a set of $N_V \equiv \text{Nvol}$ nested annular regions, which are separated by a discrete set of toroidal interfaces, \mathcal{I}_l . We insist that the fields are tangential to the interfaces. In each volume, \mathcal{V}_l , bounded by the \mathcal{I}_{l-1} and \mathcal{I}_l interfaces, the plasma energy, U_l , the global-helicity, H_l , and the mass, M_l , are given by the integrals:

$$U_l = \int_{\mathcal{V}_l} \left(\frac{p}{\gamma - 1} + \frac{B^2}{2\mu_0} \right) dv, \quad (1)$$

$$H_l = \int_{\mathcal{V}_l} \mathbf{A} \cdot \mathbf{B} dv, \quad (2)$$

$$M_l = \int_{\mathcal{V}_l} p^{1/\gamma} dv, \quad (3)$$

where $\mathbf{B} = \nabla \times \mathbf{A}$. The pressure, p , is a scalar function of position.

5. The equilibrium states that we seek [2] minimize the total plasma energy, subject to the constraints of conserved helicity and conserved mass/entropy in each annular region. We allow arbitrary variations in the pressure in each annulus, δp , the magnetic field in each annulus, $\delta \mathbf{A}$, and the geometry of the interfaces, $\boldsymbol{\xi}$, except that we assume the magnetic field remains tangential to the interfaces which we consider to act as ‘ideal barriers’.

The free-energy functional we seek to extremize is

$$F = \sum_{l=1}^{N_V} (U_l - \mu_l H_l / 2 - \nu_l M_l), \quad (4)$$

where μ_l and ν_l are Lagrange multipliers (and are constant over each volume, \mathcal{V}_l).

6. The first variation in the plasma energy, allowing variations in the pressure, δp , the field, $\delta \mathbf{A}$, and interface geometry, $\boldsymbol{\xi}$, is given

$$\delta U_l = \int_{\mathcal{V}_l} \left(\frac{\delta p}{\gamma - 1} + \frac{\mathbf{B} \cdot \nabla \times \delta \mathbf{A}}{\mu_0} \right) dv + \int_{\partial \mathcal{V}_l} \left(\frac{p}{\gamma - 1} + \frac{B^2}{2\mu_0} \right) (\mathbf{n} \cdot \boldsymbol{\xi}) ds, \quad (5)$$

Using the identity $\nabla \cdot (\mathbf{A} \times \mathbf{B}) = \mathbf{B} \cdot \nabla \times \mathbf{A} - \mathbf{A} \cdot \nabla \times \mathbf{B}$ and integrating by parts we obtain

$$\delta U_l = \int_{\mathcal{V}_l} \left(\frac{\delta p}{\gamma - 1} + \frac{\delta \mathbf{A} \cdot \nabla \times \mathbf{B}}{\mu_0} \right) dv + \int_{\partial \mathcal{V}_l} \left(\frac{p}{\gamma - 1} + \frac{B^2}{2\mu_0} \right) (\mathbf{n} \cdot \boldsymbol{\xi}) ds + \int_{\partial \mathcal{V}_l} \frac{\mathbf{n} \cdot \delta \mathbf{A} \times \mathbf{B}}{\mu_0} ds. \quad (6)$$

The interfaces are assumed to be ideal, so in the surface integrals we make use of Faraday’s law $\partial_t \mathbf{B} = \nabla \times \mathbf{E}$ and the ideal Ohm’s law $\mathbf{E} + \mathbf{v} \times \mathbf{B} = 0$ to obtain the expression $\delta \mathbf{A} = \boldsymbol{\xi} \times \mathbf{B}$. The variation in the plasma energy becomes

$$\delta U_l = \int_{\mathcal{V}_l} \left(\frac{\delta p}{\gamma - 1} + \frac{\delta \mathbf{A} \cdot \nabla \times \mathbf{B}}{\mu_0} \right) dv + \int_{\partial \mathcal{V}_l} \left(\frac{p}{\gamma - 1} - \frac{B^2}{2\mu_0} \right) (\mathbf{n} \cdot \boldsymbol{\xi}) ds. \quad (7)$$

A similar analysis shows that the first variation in the helicity is

$$\delta H_l = 2 \int_{\mathcal{V}_l} \mathbf{B} \cdot \delta \mathbf{A} dv. \quad (8)$$

The variation in the plasma mass is

$$\delta M_l = \int_{\mathcal{V}_l} \frac{p^{1/\gamma}}{\gamma p} \delta p dv + \int_{\partial \mathcal{V}_l} p^{1/\gamma} (\mathbf{n} \cdot \boldsymbol{\xi}) ds.$$

Combining these expressions, the first variation in the free-energy functional is

$$\begin{aligned}\delta F_l &= \int_{\mathcal{V}_l} \left(\frac{1}{\gamma-1} - \frac{\nu_l p^{1/\gamma}}{\gamma p} \right) \delta p \, dv \\ &+ \int_{\mathcal{V}_l} \left(\frac{\nabla \times \mathbf{B}}{\mu_0} - \mu_l \mathbf{B} \right) \cdot \delta \mathbf{A} \, dv \\ &+ \int_{\partial \mathcal{V}_l} \left(\frac{p}{\gamma-1} - \nu_l p^{1/\gamma} - \frac{B^2}{2\mu_0} \right) (\mathbf{n} \cdot \boldsymbol{\xi}) \, ds\end{aligned}\tag{9}$$

The Euler-Lagrange equation for variations in the pressure is $\nu_l p^{1/\gamma} = \gamma p / (\gamma - 1)$. For constant ν_l this indicates that $p = \text{const.}$ in each volume.

The Euler-Lagrange equation for variations in the variations in the vector-potential is the Beltrami equation, Eq.(10).

$$\nabla \times \mathbf{B} = \mu_l \mu_0 \mathbf{B}.\tag{10}$$

The Euler-Lagrange equation for variations in the interface geometry, using $\nu_l p^{1/\gamma} = \gamma p / (\gamma - 1)$, is

$$\left[\left[p + B^2 / 2\mu_0 \right] \right] = 0.\tag{11}$$

The pressure may have discrete jumps at the interfaces, and so globally non-trivial pressure profiles may be constructed, provided the total pressure, $p + B^2 / 2\mu_0$, is continuous.

7. Only the variations in the geometry normal to the interfaces, $(\mathbf{n} \cdot \boldsymbol{\xi})$, are relevant: tangential variations do not alter the energy functional. To constrain the tangential degrees of freedom, additional constraints derived from minimizing the spectral width are included.
8. An auxiliary analysis [3] indicates that, in order to support non-trivial pressure, the interfaces must have strongly irrational transform.

0.1.1 numerical discretization

1. A set of N_V nested, toroidal surfaces is given on input. For expedience, we restrict attention to stellarator symmetric devices [4] so that the interfaces may be described

$$\begin{aligned}R_l(\theta, \zeta) &= \sum_j R_{l,j} \cos(m_j \theta - n_j \zeta), \\ Z_l(\theta, \zeta) &= \sum_j Z_{l,j} \sin(m_j \theta - n_j \zeta).\end{aligned}\tag{12}$$

2. The coordinate functions $R(s, \theta, \zeta)$ and $Z(s, \theta, \zeta)$ take the form

$$\begin{aligned}R(s, \theta, \zeta) &= \sum_j R_j(s) \cos(m_j \theta - n_j \zeta), \\ Z(s, \theta, \zeta) &= \sum_j Z_j(s) \sin(m_j \theta - n_j \zeta),\end{aligned}\tag{13}$$

where the functions $R_j(s)$, $Z_j(s)$ are constructed by piecewise-cubic interpolation of the $R_{l,j}$ and $Z_{l,j}$.

3. In the l -th annulus, bounded by the $(l-1)$ -th and l -th interfaces, a general covariant representation of the magnetic vector-potential is written

$$\bar{\mathbf{A}}_l = \bar{A}_{s,l} \nabla s + \bar{A}_{\theta,l} \nabla \theta + \bar{A}_{\zeta,l} \nabla \zeta.\tag{14}$$

To this add $\nabla g_l(s, \theta, \zeta)$, where g_l satisfies

$$\begin{aligned}\partial_s g_l(s, \theta, \zeta) &= -\bar{A}_{s,l}(s, \theta, \zeta), \\ \partial_\theta g_l(s_{l-1}, \theta, \zeta) &= -\bar{A}_{\theta,l}(s_{l-1}, \theta, \zeta) + \psi_{t,l-1}, \\ \partial_\zeta g_l(s_{l-1}, 0, \zeta) &= -\bar{A}_{\zeta,l}(s_{l-1}, 0, \zeta) + \psi_{p,l-1},\end{aligned}\tag{15}$$

for arbitrary constants $\psi_{t,l-1}$, $\psi_{p,l-1}$, which are the toroidal and poloidal-fluxes on the interior of surface $l-1$. Then $\mathbf{A}_l = \bar{\mathbf{A}}_l + \nabla g_l$ is given by $\mathbf{A}_l = A_{\theta,l} \nabla \theta + A_{\zeta,l} \nabla \zeta$ with

$$\begin{aligned}A_{\theta,l}(s_{l-1}, \theta, \zeta) &= \psi_{t,l-1}, \\ A_{\zeta,l}(s_{l-1}, 0, \zeta) &= \psi_{p,l-1}.\end{aligned}\tag{16}$$

This specifies the gauge.

4. For stellarator symmetric equilibria, $A_{\theta,l}$ and $A_{\zeta,l}$ may be represented by cosine series

$$\begin{aligned} A_{\theta,l}(s, \theta, \zeta) &= \sum_j A_{\theta,l,j}(s) \cos(m_j \theta - n_j \zeta), \\ A_{\zeta,l}(s, \theta, \zeta) &= \sum_j A_{\zeta,l,j}(s) \cos(m_j \theta - n_j \zeta), \end{aligned} \tag{17}$$

where $A_{\theta,l,j}(s)$ and $A_{\zeta,l,j}(s)$ are represented using finite-elements.

0.1.2 compilation

1. The source is kept under CVS: `>cvs -d /u/shudson/cvs_Spec/ checkout Spec`
2. Compilation is provided by a Makefile: `>make xspec`. Try `>make help` for compilation options.
 - (a) The compilation flags are given by **FLAGS**. These may be over-ruled by command line arguments.
 - (b) Compilation flags must be set that convert single precision to double precision, e.g. `make FLAGS="--dbl"`.
 - (c) The NAG library is used and must be correctly linked.

readme.h last modified on 2011-10-06 ;

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- [1] S.R. Hudson, R.L. Dewar, M.J. Hole, and M. McGann. Nonaxisymmetric, multi-region relaxed magnetohydrodynamic equilibrium solutions. *Plasma Phys. Contr. F*, submitted, 2011.
 - [2] R. L. Dewar, M. J. Hole, M. Mc Gann, R. Mills, and S. R. Hudson. Relaxed plasma equilibria and entropy-related plasma self-organization principles. *Entropy*, 10:621, 2008.
 - [3] M. Mc Gann, R. L. Dewar, and S. R. Hudson. Hamilton-jacobi theory for continuation of magnetic field across a toroidal surface supporting a plasma pressure discontinuity. *Phys. Lett. A*, 2010.
 - [4] R. L. Dewar and S. R. Hudson. Stellarator symmetry. *Physica D*, 112:275, 1997.